Last Class: CPU Scheduling

- Pre-emptive versus non-preemptive schedulers
- Goals for Scheduling:
 - Minimize average response time
 - Maximize throughput
 - Share CPU equally
 - Other goals?

• Scheduling Algorithms:

- Selecting a scheduling algorithm is a policy decision consider tradeoffs
- FSCS
- Round-robin
- SJF/SRTF
- MLFQ
- Lottery scheduler

Computer Science

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Today: Threads

- What are threads?
- Where should we implement threads? In the kernel? In a user level threads package?
- How should we schedule threads (or processes) onto the CPU?



Processes versus Threads

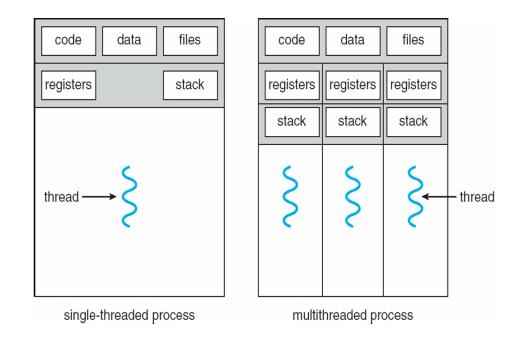
- A process defines the address space, text, resources, etc.,
- A thread defines a single sequential execution stream within a process (PC, stack, registers).
- Threads extract the *thread of control* information from the process
- Threads are bound to a single process.
- Each process may have multiple threads of control within it.
 - The address space of a process is shared among all its threads
 - No system calls are required to cooperate among threads
 - Simpler than message passing and shared-memory



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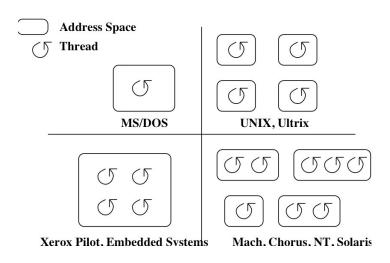
Single and Multithreaded Processes





Classifying Threaded Systems

Operating Systems can support one or many address spaces, and one or many threads per address space.





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thread 2 t stack thread 1 t stack

Example Threaded Program

global in, out, n, buffer[n]; memory layout: in = 0; out = 0;	
	tic data
	1eap
end	
producer	
repeat SP1	
nextp = produced item	
while in+1 mod n = out do no-op SP_2	
$buffer[in] = nextp; in = (in+1) \mod n$	
consumer PC,	text
repeat PC2	
while in = out do no-op nextc = buffer[out]; out = (out+1) mod n consume item nextc	femory

• Forking a thread can be a system call to the kernel, or a procedure call to a thread library (user code).



Kernel Threads

- A kernel thread, also known as a lightweight process, is a thread that the operating system knows about.
- Switching between kernel threads of the same process requires a small context switch.
 - The values of registers, program counter, and stack pointer must be changed.
 - Memory management information does not need to be changed since the threads share an address space.
- The kernel must manage and schedule threads (as well as processes), but it can use the same process scheduling algorithms.
- → Switching between kernel threads is slightly faster than switching between processes.



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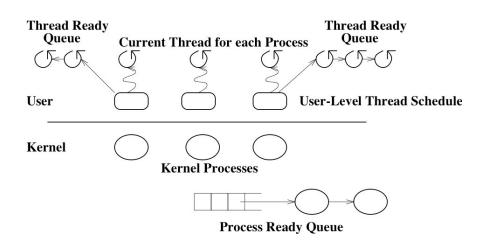
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User-Level Threads

- A user-level thread is a thread that the OS does *not* know about.
- The OS only knows about the process containing the threads.
- The OS only schedules the process, not the threads within the process.
- The programmer uses a *thread library* to manage threads (create and delete them, synchronize them, and schedule them).



User-Level Threads





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User-Level Threads: Advantages

- There is no context switch involved when switching threads.
- User-level thread scheduling is more flexible
 - A user-level code can define a problem dependent thread scheduling policy.
 - Each process might use a different scheduling algorithm for its own threads.
 - A thread can voluntarily give up the processor by telling the scheduler it will *yield* to other threads.
- User-level threads do not require system calls to create them or context switches to move between them

→ User-level threads are typically much faster than kernel threads



User-Level Threads: Disadvantages

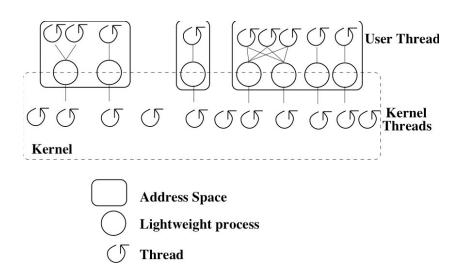
- Since the OS does not know about the existence of the user-level threads, it may make poor scheduling decisions:
 - It might run a process that only has idle threads.
 - If a user-level thread is waiting for I/O, the entire process will wait.
 - Solving this problem requires communication between the kernel and the user-level thread manager.
- Since the OS just knows about the process, it schedules the process the same way as other processes, regardless of the number of user threads.
- For kernel threads, the more threads a process creates, the more time slices the OS will dedicate to it.



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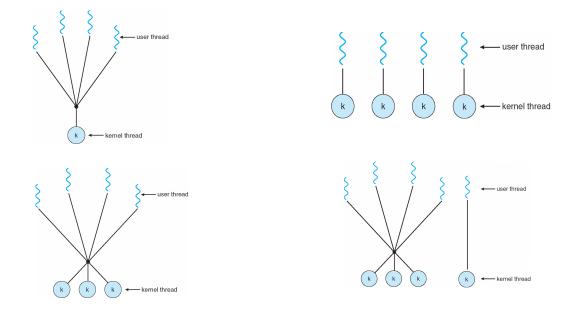
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Example: Kernel and User-Level Threads in Solaris





Threading Models



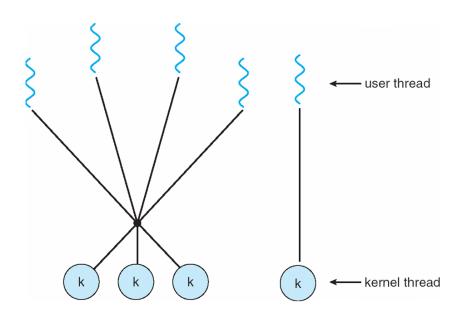
• Many-to-one, one-to-one, many-to-many and two-level



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Two-level Model





Thread Libraries

- Thread library provides programmer with API for creating and managing threads
- Two primary ways of implementing
 - Library entirely in user space
 - Kernel-level library supported by the OS



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Pthreads

- May be provided either as user-level or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization
- API specifies behavior of the thread library, implementation is up to development of the library
- Common in UNIX operating systems (Solaris, Linux, Mac OS X)
- WIN32 Threads: Similar to Posix, but for Windows



Java Threads

- Java threads are managed by the JVM
- Typically implemented using the threads model provided by underlying OS
- Java threads may be created by:
 - Extending Thread class
 - Implementing the Runnable interface



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Examples

```
Pthreads:
    pthread_attr_init(&attr); /* set default attrributes */
    pthread_create(&tid, &attr, sum, &param);
Win32 threads
ThreadHandle = CreateThread(NULL, 0, Sum, &Param, 0, &ThreadID);
Java Threads:
Sum sumObject = new Sum();
Thread t = new Thread(new Summation(param, SumObject));
```

t.start(); // start the thread

Summary

- Thread: a single execution stream within a process
- Switching between user-level threads is faster than between kernel threads since a context switch is not required.
- User-level threads may result in the kernel making poor scheduling decisions, resulting in slower process execution than if kernel threads were used.
- Many scheduling algorithms exist. Selecting an algorithm is a policy decision and should be based on characteristics of processes being run and goals of operating system (minimize response time, maximize throughput, ...).



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