

• Each track is split into *sectors* or *blocks*, the minimum unit of transfer from the disk.

Disk Overheads

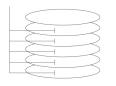
- Overhead: time the CPU takes to start a disk operation
- Latency: the time to initiate a disk transfer of 1 byte to memory.
 - Seek time: time to position the head over the correct cylinder
 - Rotational time: the time for the correct sector to rotate under the head
- Bandwidth: once a transfer is initiated, the rate of I/O transfer





How Disks Work

- CDs come individually, but disks come organized in *disk pack* consisting of a stack of platters.
- Disk packs use both sides of the platters, except on the ends.
- Comb has 2 read/write head assemblies at the end of each arm.
- Cylinders are matching sectors on each surface.
- Disk operations are in terms of radial coordinates.
 - Move arm to correct track, waiting for the disk to rotate under the head.
 - Select and transfer the correct sector as it spins by



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File Organization on Disk

The information we need:

fileID 0, Block 0 \rightarrow	Platter 0, cylinder 0, sector 0
fileID 0, Block 1 \rightarrow	Platter 4, cylinder 3, sector 8

Key performance issues:

- We need to support sequential and random access.
- What is the right data structure in which to maintain file location 2 information?
- 3. How do we lay out the files on the physical disk?



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File Organization: On-Disk Data Structures

- The structure used to describe where the file is on the disk and the attributes of the file is the *file descriptor (FileDesc)*. File descriptors have to be stored on disks just like files.
- Most systems fit the following profile:
 - 1. Most files are small.

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- 2. Most disk space is taken up by large files.
- 3. I/O operations target both small and large files.
- => The per-file cost must be low, but large files must also have good performance.

Contiguous Allocation

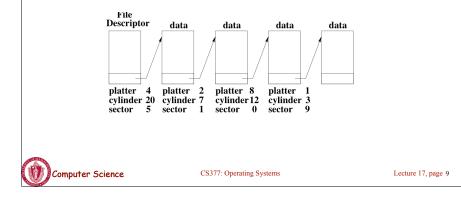
- OS maintains an ordered list of free disk blocks
- OS allocates a contiguous chunk of free blocks when it creates a file.
- Need to store only the start location and size in the file descriptor
- Advantages
- Simple,
- Access time? Number of seeks?
- Disadvantages
 - Changing file sizes
 - Fragmentation? Disk management?
- **Examples:** IBM OS/360, write-only disks, early personal computers





Linked files

- Keep a list of all the free sectors/blocks.
- In the file descriptor, keep a pointer to the first sector/block.
- In each sector, keep a pointer to the next sector.



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Indexed files

- OS keeps an array of block pointers for each file.
- The user or OS must declare the maximum length of the file when it is created.
- OS allocates an array to hold the pointers to all the blocks when it creates the file, but allocates the blocks only on demand.
- OS fills in the pointers as it allocates blocks.



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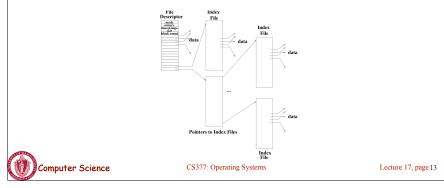
Indexed files

- Advantages
 - Not much wasted space.
 - Both sequential and random accesses are easy.
- Disadvantages
 - Sets a maximum file size.
 - Lots of seeks because data is not contiguous.
- Examples: Nachos



Multilevel indexed files

- · Each file descriptor contains 14 block pointers.
- First 12 pointers point to data blocks.
- 13th pointer points to a block of 1024 pointers to 1024 more data blocks. (One indirection)
- 14th pointer points to a block of pointers to indirect blocks. (Two indirections)



Multilevel indexed files: BSD UNIX 4.3

- Advantages
 - Simple to implement
 - Supports incremental file growth
 - Small files?
- Disadvantages
 - Indirect access is inefficient for random access to very large files.
 - Lots of seeks because data is not contiguous.
- Is the file size bounded?
- What could the OS do to get more contiguous access and fewer seeks?



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Free-Space Management

- Need a free-space list to keep track of which disk blocks are free (just as we need a free-space list for main memory)
- Need to be able to find free space quickly and release space quickly => use a bitmap
 - The bitmap has one bit for each block on the disk.
 - If the bit is 1, the block is free. If the bit is 0, the block is allocated.
- Can quickly determine if any page in the next 32 is free, by comparing the word to 0. If it is 0, all the pages are in use. Otherwise, you can use bit operations to find an empty block. 110000100100011111110...
- Marking a block as freed is simple since the block number can be used to index into the bitmap to set a single bit.

Free-Space Management

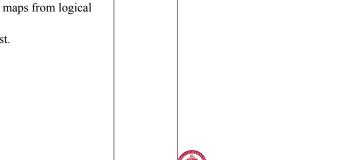
- **Problem:** Bitmap might be too big to keep in memory for a large disk. A 2 GB disk with 512 byte sectors requires a bitmap with 4,000,000 entries (500,000 bytes).
- If most of the disk is in use, it will be expensive to find free blocks with a bitmap.
- An alternative implementation is to link together the free blocks.
 - The head of the list is cached in kernel memory. Each block contains a pointer to the next free block.
 - How expensive is it to allocate a block?
 - How expensive is it to free a block?
 - How expensive is it to allocate consecutive blocks?





Summary

- Many of the concerns and implementations of file system implementations are similar to those of virtual memory implementations.
 - Contiguous allocation is simple, but suffers from external fragmentation, the need for compaction, and the need to move files as they grow.
 - Indexed allocation is very similar to page tables. A table maps from logical file blocks to physical disk blocks.
 - Free space can be managed using a bitmap or a linked list.



Deadlocks

Memory Management

Deadlocks

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- What is a deadlock? Difference from starvation
- Necessary conditions for a deadlock
- Deadlock detection, avoidance, prevention
- Resource allocation graph deadlock detection
- Concept of a safe state
- Banker's algorithm

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- Problem solving with banker's algorithm

Memory Management

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Exam Review

Topics you should understand:

- 1. What is virtual memory and why do we use it?
- 2. Memory allocation strategies:
 - Relocation and Contiguous allocation (first-fit and best-fit algorithms)
 - Paging

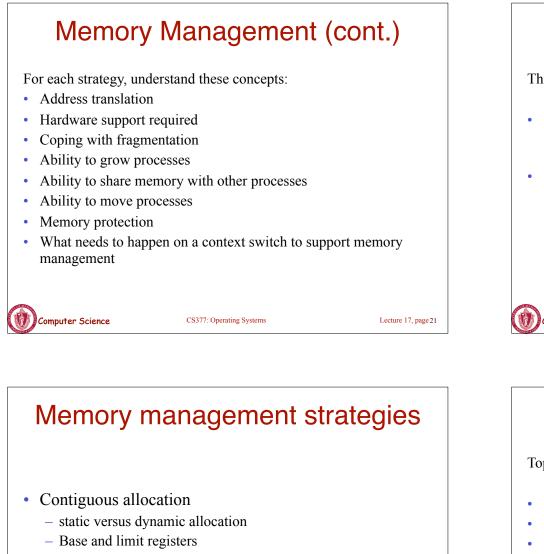
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- Segmentation
- Paged segmentation
- Demand paging



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Memory Management (cont.)

Things you should be able to do:

- Given a request for memory, determine how the request can be satisfied using contiguous allocation.
- Given a virtual address and the necessary tables, determine the corresponding physical address.



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- Best, first, worst-fit strategies

Paging and Segmentation

Topics you should understand:

- What is paging, a page, a page frame?
- What does the OS store in the page table?
- What is a TLB? How is one used?
 - Effective memory access times using a TLB
- What is segmentation? where are segment tables stored?
- How to combine segmentation and paging?
- What is demand paging?
- What is a page fault, how does the OS know it needs to take one, and what does the OS do when a page fault occurs?





Paging (cont.)

- Page replacement algorithms. For each understand how they work, advantages, disadvantages, and hardware requirements.
 - 1. FIFO
 - 2. MIN
 - 3. LRU
 - 4. Second chance
 - 5. Enhanced second chance
- How do global and per-process (aka local) allocation differ?
- What is temporal locality? What is spatial locality? What effect do these have on the performance of paging?
- What is a working set?



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Paging (cont.)

- What is thrashing and what are strategies to eliminate it?
- What considerations influence the page size that should be used?

Things you should be able to do:

1. Given a page reference string and a fixed number of page frames, determine how the different replacement algorithms would handle the page faults.



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