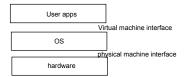
# Last 2 Classes: Introduction to Operating Systems & C++ tutorial



- An operating system is the interface between the user and the architecture.
  - History lesson in change.
  - OS reacts to changes in hardware, and can motivate changes.



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# Today: OS and Computer Architecture

- Basic OS Functionality
- Basic Architecture reminder
- What the OS can do is dictated in part by the architecture.
- Architectural support can greatly simplify or complicate the OS.



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# **Modern Operating System Functionality**

- 1. Concurrency: Doing many things simultaneously (I/0, processing, multiple programs, etc.)
  - Several users work at the same time as if each has a private machine
  - Threads (unit of OS control) one thread on the CPU at a time, but many threads active concurrently
- 2. I/O devices: let the CPU work while a slow I/O device is working
- **3. Memory management**: OS coordinates allocation of memory and moving data between disk and main memory.
- **4. Files:** OS coordinates how disk space is used for files, in order to find files and to store multiple files
- 5. **Distributed systems & networks:** allow a group of workstations to work together on distributed hardware



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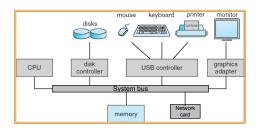
## Summary of Operating System Principles

- **OS as juggler:** providing the illusion of a dedicated machine with infinite memory and CPU.
- OS as government: protecting users from each other, allocating resources efficiently and fairly, and providing secure and safe communication.
- OS as complex system: keeping OS design and implementation as simple as possible is the key to getting the OS to work.
- OS as history teacher: learning from past to predict the future, i.e., OS design tradeoffs change with technology.



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# **Generic Computer Architecture**



- **CPU:** the processor that performs the actual computation
- I/O devices: terminal, disks, video board, printer, etc.
- Memory: RAM containing data and programs used by the CPU
- **System bus:** communication medium between CPU, memory, and peripherals



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# Architectural Features Motivated by OS Services

OS Service	Hardware Support
Protection	Kernel/user mode, protected instructions, base/limit registers
Interrupts	Interrupt vectors
System calls	Trap instructions and trap vectors
I/O	Interrupts and memory mapping
Scheduling, error recovery, accounting	Timer
Syncronization	Atomic instructions
Virtual memory	Translation look-aside buffers



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#### **Protection**

**Kernel mode vs. User mode:** To protect the system from aberrant users and processors, some instructions are restricted to use only by the OS. Users may not

- address I/O directly
- use instructions that manipulate the state of memory (page table pointers, TLB load, etc.)
- set the mode bits that determine user or kernel mode
- disable and enable interrupts
- halt the machine

but in kernel mode, the OS can do all these things.

The hardware must support at least kernel and user mode.

- A status bit in a protected processor register indicates the mode.
- Protected instructions can only be executed in kernel mode.

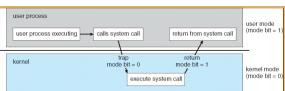


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# **Crossing Protection Boundaries**

- **System call:** OS procedure that executes privileged instructions (e.g., I/O)
  - Causes a trap, which vectors (jumps) to the trap handler in the OS kernel.
  - The trap handler uses the parameter to the system call to jump to the appropriate handler (I/O, Terminal, etc.).
  - The handler saves caller's state (PC, mode bit) so it can restore control to the user process.
  - The architecture must permit the OS to verify the caller's parameters.
  - The architecture must also provide a way to return to user mode when finished.

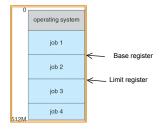


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# **Memory Protection**

- Architecture must provide support so that the OS can
  - protect user programs from each other, and
  - protect the OS from user programs.
- The simplest technique is to use base and limit registers.
- Base and limit registers are loaded by the OS before starting a program.
- The CPU checks each user reference (instruction and data addresses), ensuring it falls between the base and limit register values



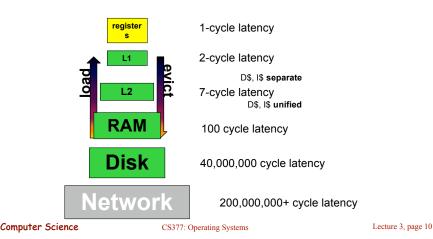


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# **Memory Hierarchy**

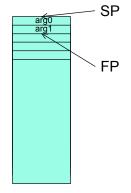
- Higher = small, fast, more \$, lower latency
- Lower = large, slow, less \$, higher latency



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# Registers

- Register = dedicated name for one word of memory managed by CPU
  - General-purpose: "AX", "BX", "CX" on x86
  - Special-purpose:
    - "SP" = stack pointer
    - "FP" = frame pointer
    - "PC" = program counter
- Change processes: save current registers & load saved registers = context switch





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#### Caches

- Access to main memory: "expensive"
  - $\sim 100$  cycles (slow, but relatively cheap (\$))
- Caches: small, fast, expensive memory
  - Hold recently-accessed data (D\$) or instructions (I\$)
  - Different sizes & locations
    - Level 1 (L1) on-chip, smallish
    - Level 2 (L2) on or next to chip, larger
    - Level 3 (L3) pretty large, on bus
  - Manages lines of memory (32-128 bytes)



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# **Traps**

- Traps: special conditions detected by the architecture
  - Examples: page fault, write to a read-only page, overflow, systems call
- On detecting a trap, the hardware
  - Saves the state of the process (PC, stack, etc.)
  - Transfers control to appropriate trap handler (OS routine)
    - The CPU indexes the memory-mapped trap vector with the trap number,
    - then jumps to the address given in the vector, and
    - starts to execute at that address.
    - On completion, the OS resumes execution of the process



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# **Traps**

Trap Vector:

0: 0x00080000 1: 0x00100000 2: 0x00100480 3: 0x00123010 Illegal address Memory violation Illegal instruction System call

- Modern OS use Virtual Memory traps for many functions: debugging, distributed VM, garbage collection, copy-on-write, etc.
- Traps are a performance optimization. A less efficient solution is to insert extra instructions into the code everywhere a special condition could arise.



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## I/O Control

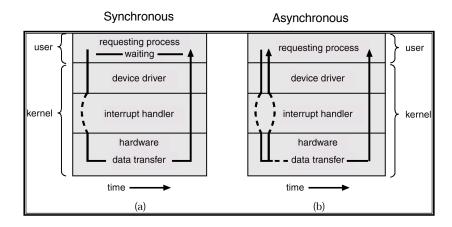
- Each I/O device has a little processor inside it that enables it to run autonomously.
- CPU issues commands to I/O devices, and continues
- When the I/O device completes the command, it issues an interrupt
- CPU stops whatever it was doing and the OS processes the I/O device's interrupt



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# Two I/O Methods



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# Memory-Mapped I/O

- Enables direct access to I/O controller (vs. being required to move the I/O code and data into memory)
- PCs (no virtual memory), reserve a part of the memory and put the device manager in that memory (e.g., all the bits for a video frame for a video controller).
- Access to the device then becomes almost as fast and convenient as writing the data directly into memory.



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# Interrupt based asynchronous I/O

- Device controller has its own small processor which executes asynchronously with the main CPU.
- Device puts an interrupt signal on the bus when it is finished.
- CPU takes an interrupt.
  - 1. Save critical CPU state (hardware state),
  - 2. Disable interrupts,
  - 3. Save state that interrupt handler will modify (software state)
  - 4. Invoke interrupt handler using the in-memory Interrupt Vector
  - 5. Restore software state
  - 6. Enable interrupts
  - 7. Restore hardware state, and continue execution of interrupted process



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## **Timer & Atomic Instructions**

#### Timer

- Time of Day
- Accounting and billing
- CPU protected from being hogged using timer interrupts that occur at say every 100 microsecond.
- At each timer interrupt, the CPU chooses a new process to execute.

#### **Interrupt Vector:**

0: 0x2ff080000	keyboard
1: 0x2ff100000	mouse
2: 0x2ff100480	timer
3: 0x2ff123010	Disk 1



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# Synchronization

- Interrupts interfere with executing processes.
- OS must be able to synchronize cooperating, concurrent processes.
- → Architecture must provide a guarantee that short sequences of instructions (e.g., read-modify write) execute atomically. Two solutions:
  - 1. Architecture mechanism to disable interrupts before sequence, execute sequence, enable interrupts again.
  - 2. A special instruction that executes atomically (e.g., test&set)



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# Virtual Memory

- Virtual memory allows users to run programs without loading the entire program in memory at once.
- Instead, pieces of the program are loaded as they are needed.
- The OS must keep track of which pieces are in which parts of physical memory and which pieces are on disk.
- In order for pieces of the program to be located and loaded without causing a major disruption to the program, the hardware provides a translation lookaside buffer to speed the lookup.



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# **Summary**

Keep your architecture book on hand.

- OS provides an interface to the architecture, but also requires some additional functionality from the architecture.
- → The OS and hardware combine to provide many useful and important features.



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