

Last Class: Synchronization

- Synchronization primitives are required to ensure that only one thread executes in a critical section at a time.

Concurrent Programs		Low-level atomic operations (hardware)	High-level atomic operations (software)
load/store	interrupt disable	test&set	semaphores
monitors	send & receive	locks	semaphores

Today: Synchronization: Locks and Semaphores

- More on hardware support for synchronization
- Implementing locks using test&set and busy waiting
- What are semaphores?

- Semaphores are basically generalized locks.
- Like locks, semaphores are a special type of variable that supports two atomic operations and offers elegant solutions to synchronization problems.
- They were invented by Dijkstra in 1965.

Atomic read-modify-write instructions

- Atomic read-modify-write instructions *atomically* read a value from memory into a register and write a new value.
 - Straightforward to implement simply by adding a new instruction on a uniprocessor.
 - On a multiprocessor, the processor issuing the instruction must also be able to *invalidate* any copies of the value the other processes may have in their cache, i.e., the multiprocessor must support some type of *cache coherence*.
- **Examples:**
 - **Test&Set:** (most architectures) read a value, write '1' back to memory.
 - **Exchange:** (x86) swaps value between register and memory.
 - **Compare&Swap:** (68000) read value, if value matches register value r1, exchange register r2 and value.

Implementing Locks with Test&Set

- **Test&Set:** reads a value, writes '1' to memory, and returns the old value.


```
class Lock {
public:
    void Acquire();
    void Release();
private:
    int value;
};
Lock::Lock {
    value = 0;
}
Lock::Acquire() {
    // if busy do nothing
    while (test&set(value) == 1);
}
Lock::Release() {
    value = 0;
}
}
Lock::Lock {
    value = 0;
}
}
```
- If lock is free (value = 0), test&set reads 0, sets value to 1, and returns 0. The Lock is now busy: the test in the while fails, and Acquire is complete.
- If lock is busy (value = 1), test&set reads 1, sets value to 1, and returns 1. The while continues to loop until a Release executes.

Busy Waiting

```
Lock::Acquire(){
    //if Busy, do nothing
    while (test&set(value) == 1);
}
```

- What's wrong with the above implementation?
 - What is the CPU doing?
 - What could happen to threads with different priorities?
- How can we get the waiting thread to give up the processor, so the releasing thread can execute?

- Can we implement locks with test&set without any busy-waiting or disabling interrupts?

- No, but we can minimize busy-waiting time by atomically checking the lock value and giving up the CPU if the lock is busy

Locks using Test&Set with minimal busy-waiting

```
class Lock {
    // same declarations as earlier
    private int guard;
}
Lock::Acquire(T:Thread) {
    while (test&set(guard) == 1) ;
    if (value != FREE) {
        put T on q;
        T->Sleep() & set guard = 0;
    } else {
        value = BUSY;
        guard = 0;
    }
}
Lock::Release() {
    // busy wait
    while (test&set(guard) == 1) ;
    if q is not empty {
        take T off q;
        put T on ready queue;
    } else {
        value = FREE;
    }
    guard = 0;
}
```

Semaphores

- **Semaphore**: an integer variable that can be updated only using two special atomic instructions.

- **Binary (or Mutex) Semaphore**: (same as a lock)

- Guarantees mutually exclusive access to a resource (only one process is in the critical section at a time).
- Can vary from 0 to 1
- It is initialized to free (value = 1)

- **Counting Semaphore**:

- Useful when multiple units of a resource are available
- The initial count to which the semaphore is initialized is usually the number of resources.
- A process can acquire access so long as at least one unit of the resource is available

Semaphores: Key Concepts

- Like locks, a semaphore supports two atomic operations, Semaphore->Wait() and Semaphore->Signal().

```
S->Wait() // wait until semaphore S
          // is available
<critical section>
```

```
S->Signal() // signal to other processes
           // that semaphore S is free
```

- Each semaphore supports a queue of processes that are waiting to access the critical section (e.g., to buy milk).
- If a process executes **S->Wait()** and semaphore S is free (non-zero), it continues executing. If semaphore S is not free, the OS puts the process on the wait queue for semaphore S.
- **A S->Signal()** unblocks one process on semaphore S's wait queue.

Binary Semaphores: Example

- Too Much Milk using locks:

```

Thread A
lock->Acquire();
if (nomilk) {
    buy milk;
}
lock->Release();

Thread B
lock->Acquire();
if (nomilk) {
    buy milk;
}
lock->Release();

```

- Too Much Milk using semaphores:

```

Thread A
Semaphore->Wait();
if (nomilk) {
    buy milk;
}
Semaphore->Signal();

Thread B
Semaphore->Wait();
if (nomilk) {
    buy milk;
}
Semaphore->Signal();

```

Implementing Signal and Wait

```

class Semaphore {
public:
    void Wait(Process P);
    void Signal();
private:
    int value;
    Queue Q; // queue of processes;
    Semaphore::Signal() {
        if (
            add P to Q;
            P->block();
        }
    }
    Semaphore::Wait(Process P) {
        value = value - 1;
        if (value < 0) {
            add P to Q;
            P->block();
        }
    }
    Semaphore::Signal() {
        value = value + 1;
        if (value >= 0) {
            remove P from Q;
            wakeup(P);
        }
    }
}

⇒ Signal and Wait of course must be atomic

```

Signal and Wait: Example

P1: S->Wait();
 P1: S->Wait();
 P2: S->Wait();
 P2: S->Wait();
 P1: S->Signal();
 P1: S->Signal();
 P2: S->Signal();

process state:	value	Queue	execute	execute
execute or block	2	empty	P1	P2

P1: S->Wait();
 P2: S->Wait();
 P1: S->Wait();
 P1: S->Signal();
 P2: S->Signal();
 P1: S->Signal();

value	Queue	execute	execute
2	empty	P1	P2

Using Semaphores

- **Mutual Exclusion:** used to guard critical sections
 - the semaphore has an initial value of 1
 - S->Wait() is called before the critical section, and S->Signal is called after the critical section.
- **Scheduling Constraints:** used to express general scheduling constraints where threads must wait for some circumstance.
 - The initial value of the semaphore is usually 0 in this case.
 - **Example:** You can implement thread *join* (or the Unix system call *waitpid*(PID)) with semaphores:


```

Semaphore S;
S->value = 0; // semaphore initialization
Thread::Join Thread::Finish
S->Signal();
          
```

```

class BoundedBuffer {
public:
    void Producer();
    void Consumer();
private:
    Items *buffer;
    // control access to buffers
    Semaphore mutex;
    // count of free slots
    Semaphore empty;
    // count of used slots
    Semaphore full;
    BoundedBuffer(int N){
        mutex->Wait(); // wait until there's an item
        full->Wait(); // wait until there's an item
        mutex->Wait(); // get access to buffers
        <remove item from buffer>
        mutex->Signal(); // release buffers
        empty->Signal(); // one more free slot
    }
    BoundedBuffer::Consumer(){
        full->Wait(); // wait until there's an item
        mutex->Wait(); // get access to buffers
        <add item to buffer>
        mutex->Signal(); // release buffers
        full->Signal(); // one more used slot
    }
};

BoundedBuffer::Producer(){
    <produce item>
    empty->Wait(); // one fewer slot, or wait
    mutex->Wait(); // get access to buffers
    <add item to buffer>
    mutex->Signal(); // release buffers
    full->Signal(); // one more used slot
}

BoundedBuffer::Consumer(){
    // count of used slots
    Semaphore full;
    // count of free slots
    Semaphore empty;
    // count of used slots
    Semaphore full;
}

BoundedBuffer(int N){
    mutex->Wait(); // wait until there's an item
    mutex->Wait(); // get access to buffers
    <remove item from buffer>
    mutex->Signal(); // release buffers
    empty->Signal(); // one more free slot
}

new buffer[N];
}
    
```

Multiple Consumers and Producers

- Locks can be implemented by disabling interrupts or busy waiting
- Semaphores are a generalization of locks
- Semaphores can be used for three purposes:
 - To ensure mutually exclusive execution of a critical section (as locks do).
 - To control access to a shared pool of resources (using a counting semaphore).
 - To cause one thread to wait for a specific action to be signaled from another thread.

Summary

initially	● ● ● ● ●	○ ○ ○ ○ ○
Producer 1	● ● ● ● ●	○
...	full->signal();	○ ○ ○ ○ ●
Producer 2	● ● ● ● ●	○ ○
...	empty->wait();	○ ○ ● ● ●
Consumer		○ ○ ○ ○ ●
...	full->wait();	○ ● ● ● ●
empty->signal();	○ ● ● ● ●	○ ○ ○ ○ ○
full	empty	full

Multiple Consumers and Producers Problem