

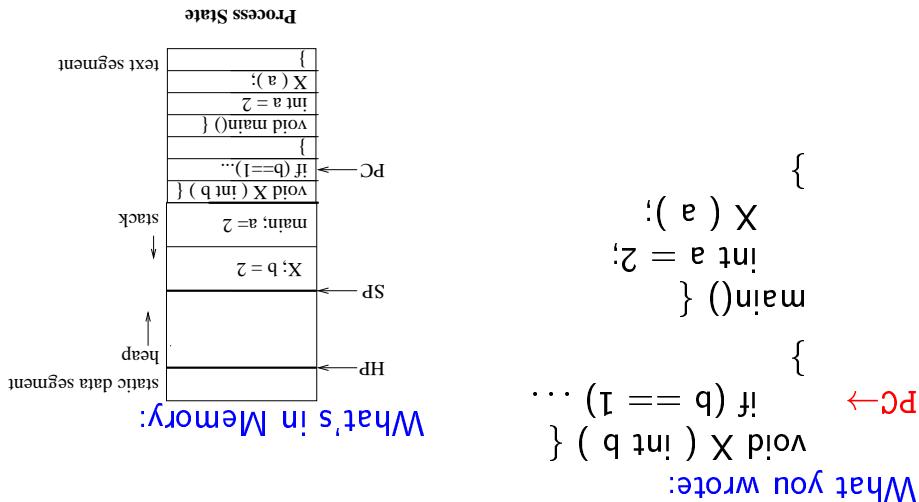
- How do processes communicate? Is this efficient?
- What are possible execution states and how does the system move from one state to another?
- How are processes represented in the OS?
- A process as the unit of execution.

Todays: Process Management

Hardware	Abstract	Example OS Services	User Abstraction
Processor	Process management, Scheduling, Protection, Billing,	Traps Protection, Synchronization	Address space
Memory	Memory management, Protection, Virtual	Management, Protection, Billing,	Virtual memory
I/O devices	Concurrency with CPU, interrupt handling	Terminal, Mouse, Printer,	System Calls
File system	Management, Persistence	Files	RPC system calls, file sharing
Distributed systems	Network security, Distributed file		

From the Architecture to the OS to the User: Architectural resources, OS management, and User Abstractions.

The Big Picture So Far



Example Process State in Memory

- **Processes**: dynamic execution context of an executing program
- Several processes may run the same program, but each is a distinct process with its own state (e.g., MS Word).
- A process executes sequentially, one instruction at a time
- Process state consists of at least:
 - the code for the running program,
 - the static data for the running program,
 - space for dynamic data (the heap), the heap pointer (HP),
 - the Program Counter (PC), indicating the next instruction,
 - an execution stack with the program's call chain (the stack), the stack pointer (SP)
 - values of CPU registers
 - a set of OS resources in use (e.g., open files)
 - process execution state (ready, running, etc.).

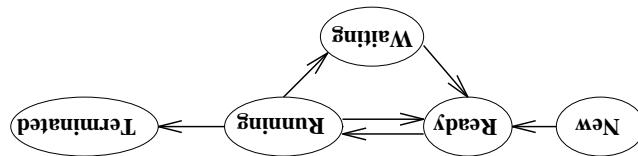
What's in a Process?

(More on this in a minute ...)

- The OS manages multiple active processes using **state queues**

```
state sequence
new
ready
running
waiting for I/O
ready
running
ready
new
void main() {
    printf("Hello World\n");
}
```

Example:



Process Execution State

- DEPARTMENT OF COMPUTER SCIENCE, MASSACHUSETTS
- CMPSCI 377: OPERATING SYSTEMS Lecture 4, Page 5
- As the program executes, it moves from state to state, as a result of the external actions (interrupts), OS actions (scheduling), and program actions (e.g., system calls), OS actions (scheduling), and external actions (interrupts).
- new: the OS is setting up the process state
running: executing instructions on the CPU
ready: ready to run, but waiting for the CPU
waiting: waiting for an event to complete (e.g., I/O)
terminated: the OS is destroying this process

Process Execution State

- Each I/O device has its own wait queue.
- The OS can use different policies to manage each queue.
- When the OS changes the state of a process, the PCB is unlinked from its current queue and moved to its new state queue.
- The OS places the PCBs of all the processes in the same *execution state* in the same queue.
- The OS maintains the PCBs of all the processes in *state queues*.

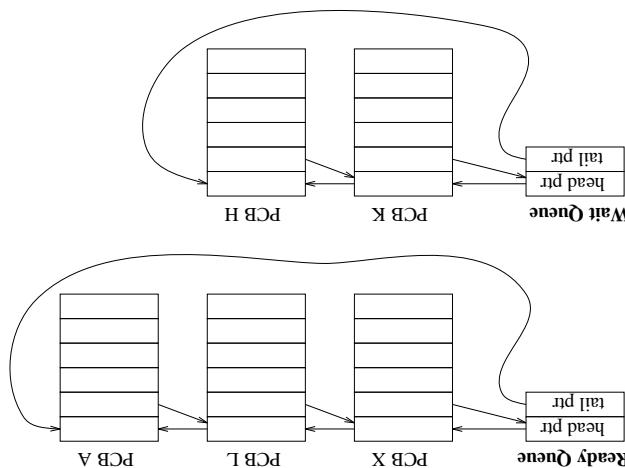
Process State Queues

- The PCB contains:
 - The OS deallocates the PCB when the process terminates
 - The OS allocates a new PCB on the creation of each process and places it on a state queue
 - The PCB tracks the execution state and location of each process
- Processes Control Block (PCB): OS data structure to keep track of all processes
 - Process state (running, waiting, etc.)
 - User name of owner
 - List of open files
 - Program Counter
 - Stack Pointer
 - General Purpose Registers
 - Queue pointers for state queues
 - Scheduling information (e.g., priority)
 - I/O status
 - Memory Management Information
 - ...

Process Data Structures

- The cost of a context switch and the time between switches are closely related.
- Time sharing systems may do 100 to 1000 context switches a second.
- This process of switching the CPU from one process to another (stopping one and starting the next) is the context switch.
- When the OS stops a process, it saves the current values of the registers, (PC, SP, etc.) into its PCB.
- While a process is running, the CPU modifies the Program Counter (PC), Stack Pointer (SP), registers, etc.
- The OS starts executing a ready process by loading hardware registers (PC, SP, etc) from its PCB.
- Starting and stopping processes is called a **context switch**, and is a relatively expensive operation.

PCBs and Hardware State



State Queues: Example

- If you type an & after the command, Unix will run the process in parallel with your shell, otherwise, your next shell command must wait until the first one completes.
- For example, you type emacs, the OS "forks" a new process and then "exec" (executes) emacs.
- Every command you type into the shell is a child of your shell process and is an implicit fork and exec pair.
- When you log in to a machine running Unix, you create a shell process.

Creating a Process: Example

- In Unix, the `fork` system call is used to create child processes
 - Fork copies variables and registers from the parent to the child
 - The only difference between the child and the parent is the value returned by `fork`
 - * In the parent process, `fork` returns the process id of the child
 - * In the child process, the return value is 0
 - The parent can wait for the child by executing the `wait` system call or continue execution
 - The child often starts a new and different program within itself, via a call to `exec` system call.
- One process can create other processes to do work.

Creating a Process

`gets()` reads a line from a file.

`waitpid()` waits for the named process to finish execution.

`sleep()` suspends execution for at least the specified time.

`execvp()` replaces the program of the current process with the named program.

`fork()` forks a new child process that is a copy of the parent.

Example Unix Program: Explanation

```

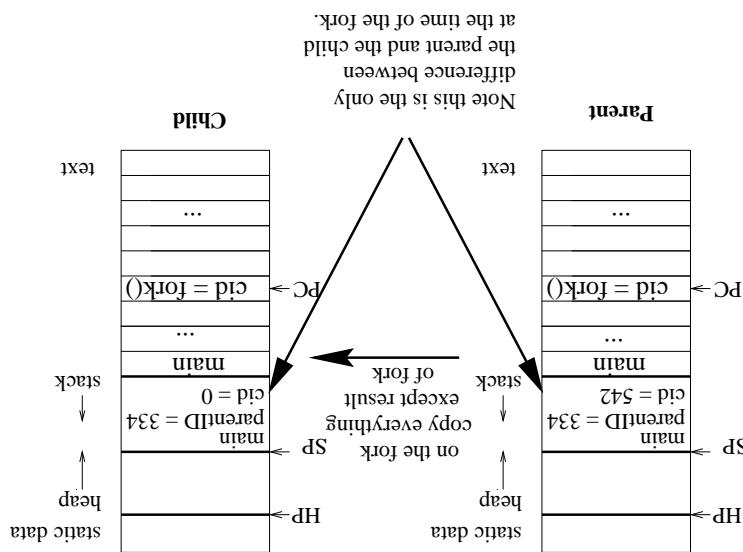
main() {
    #include <sys/wait.h>
    #include <unistd.h>
    int parentID = getpid(); /* ID of this process */
    char progrname[1024];
    gets(progrname); /* read the name of program we want to start */
    if(cid == 0) { /* I, m the child process */
        execvp(progrname, progrname, 0); /* Load the program */
        /* If the program named progrname can be started, we never get
         * to this line, because the child program is replaced by progrname */
        printf("I didn't find program %s\n", progrname);
    } else { /* I, m the parent process */
        sleep(1); /* Give my child time to start. */
        waitpid(cid, 0); /* Wait for my child to terminate. */
        printf("Program %s finished\n", progrname);
    }
}

```

Example Unix Program: Fork

- a process can terminate a child using the `kill` system call.
- a process can terminate itself using the `exit` system call.
- In Unix
 - On process termination, the OS reclaims all resources assigned to the process.

Process Termination



What is happening on the Fork

⇒ Distributed and parallel processing is the wave of the future. To program these machines, we must cooperate and coordinate between separate processes.

- Any two processes are either independent or cooperative
 - Cooperative processes work with each other to accomplish a single task.
 - Cooperative processes can improve performance by overlapping activities or performing work in parallel.
 - Enable an application to achieve a better program structure as a set of cooperating processes, where each is smaller than a single monolithic program, and easily share information between tasks.

Cooperating Processes

```

#include <sigreal.h>
#include <unistd.h>
#include <stro.h>

main() {
    int parentID = getpid(); /* ID of this process */
    int cild = fork();
    if (cild == 0) { /* I,m the child process */
        sleep(5); /* I,ll exit myself after 5 seconds. */
        printf("QUITTING child\n");
        exit(0);
    }
    else { /* I,m the parent process */
        if (cild == 0) { /* I,m the child */
            sleep(5); /* I,ll exit myself after 5 seconds. */
            printf("QUITTING child\n");
            exit(0);
        }
        else { /* I,m the parent */
            char answer[10];
            printf("Type any character to kill the child.\n");
            gets(answer);
            if (kill(cild, SIGKILL) ) {
                printf("Killed the child.\n");
            }
        }
    }
}

```

Example Unix Program: Process Termination

```
main()
{
    if (fork() != 0) producerSR();
    else consumerSR();
    end
    ...
    if (fork() != 0) producerSR();
    else consumerSR();
    repeat
        receive (nextc, producer)
        produce item nextp
        ...
        consume item nextc
    ...
    send (nextp, consumer)
    ...
}
```

Communication using Message Passing

- Producers and consumers can communicate using **message passing** or **shared memory**

Cooperating Processes: Producers and Consumers

- Fork processes that need to share the data structure.
- The map(. . .) systems call performs this function.
- Establish a mapping between the process's address space to a named memory object that may be shared across processes

Communication using Shared Memory

- multiple consumers?
- ⇒ How would you use message passing to implement a single producer and
- OS keeps track of messages (copies them, notifies receiving process, etc.).
 - A bounded buffer would require the tests in the previous slide, and communication of the in and out variables (in from producer to consumer, out from consumer to producer).
 - The consumer is assumed to have an infinite buffer size.
 - Each process needs to be able to name the other process.
 - Distributed systems typically communicate using message passing

Message Passing

- Processes communicate either with message passing or shared memory
- The program currently executing on the CPU is changed by performing a context switch
- On a uniprocessor, there is at most one running process at a time.
- A process is either New, Ready, Waiting, Running, or Terminated.
- PCBs contain process state, scheduling and memory management information, etc
- Processes are represented as Process Control Blocks in the OS
- A process is the unit of execution.

Process Management: Summary

```

main()
{
    map(..., in, out, PROT_WRITE, MAP_SHARED, ...);
    ...
    if (fork() != 0) producer();
    else consumer();
    out = 0;
    in = 0;
    repeat
    {
        while (in == out) do_no_op();
        produce_item(nextp);
        nextc = buffer[out];
        out = out + 1 mod n;
        ...
        while (in + 1 mod n == out) do_no_op();
        in = in + 1 mod n;
        ...
        consume_item(nextc);
        buffer[in] = nextp;
        ...
    }
    end
}

```

Shared Memory Example